

Compilation (#6a) : SSA

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Master 1, ENS de Lyon et Dpt Info, Lyon1

2024-2025



- 1 SSA Control Flow Graph
- 2 LAB: CFG + SSA
- 3 Exercises

Credits

Source <http://homepages.dcc.ufmg.br/~fernando/classes/dcc888/ementa/slides/StaticSingleAssignment.pdf>

- The SSA book (collective)
- Modern Compiler Implementation in C/Java/ML (Andrew Appel)
- Fernando Magno Quintao Pereira's course
<https://www.youtube.com/user/pronesto/videos>
- Adrian Sampson's course
<https://www.cs.cornell.edu/courses/cs6120/2020fa/>

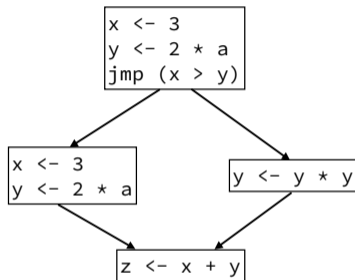
Motivation: It's all about information

Compilers alternate between two tasks:

1. *computing* some information (invariants) of the program
2. *using* this information to justify some program transformations

Dataflow analyses associate facts to every program point:

- * a fact is *associated* to a *definition-site* of a variable
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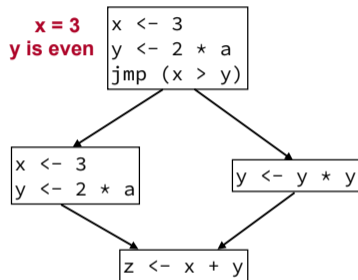
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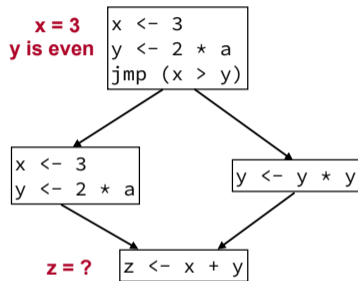
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What do we know about x and y?

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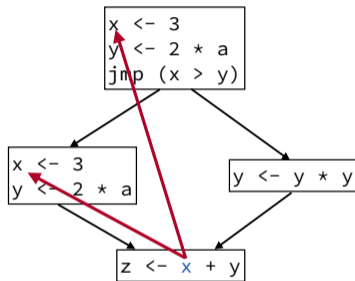
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M def and **N** use of a variable: $O(N * M)$ space and time



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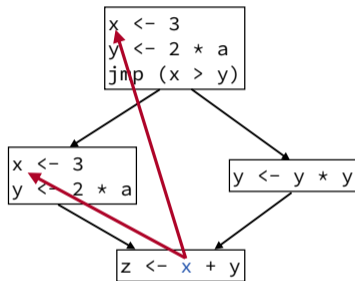
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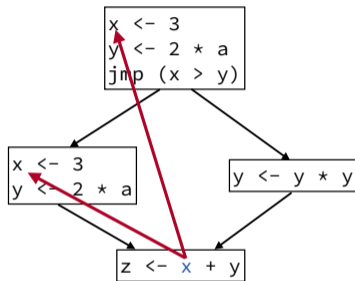
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We want to enforce an invariant by construction: we want an *intermediate representation*

Single Static Assignment (SSA)

Each variable has **exactly one definition** in the syntax¹

Use-def chains are explicit in the syntax of the program -> Many optimizations are simplified

¹ Dynamically, it can be defined many times: it is not “Single Assignment”!

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Introduced in 1988:

“Global value numbers and redundant computations” by Rosen, Wegman and Zadeck

Used in most modern compilers: GCC, llvm, HotSpot...

We will consider here more specifically Control Flow Graphs in SSA form

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Converting to SSA form: informally

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Converting straight code

bl:

```
a <- x + 1
b <- a * 2
a <- a + b
c <- x * a
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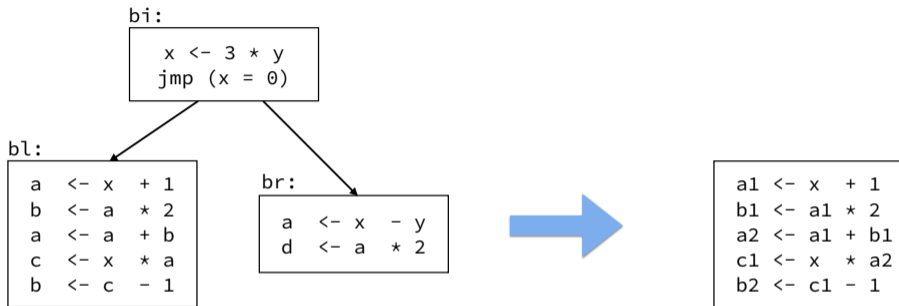
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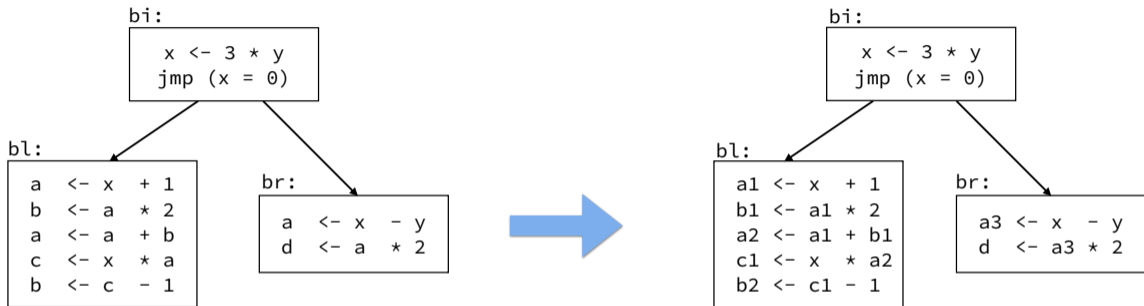
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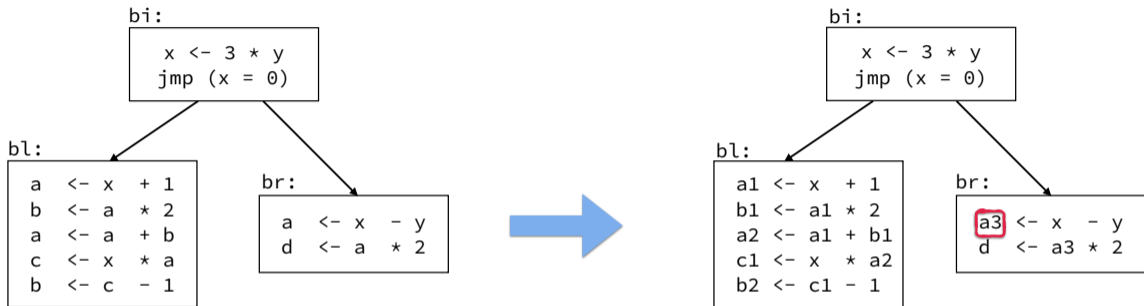
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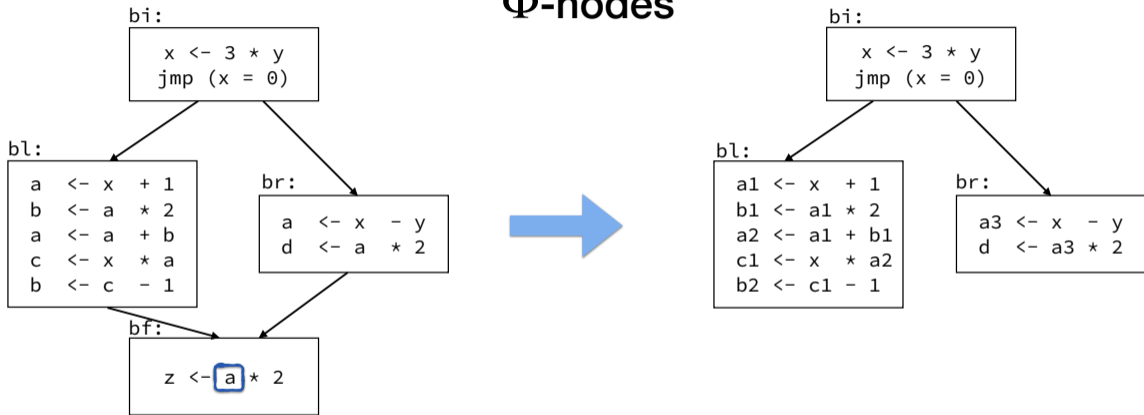


Freshness is global

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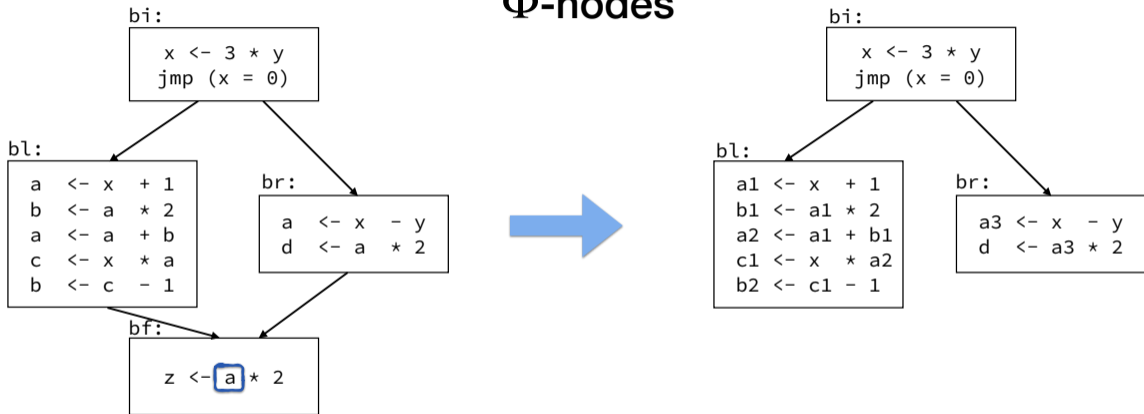
Converting merging points: Φ -nodes



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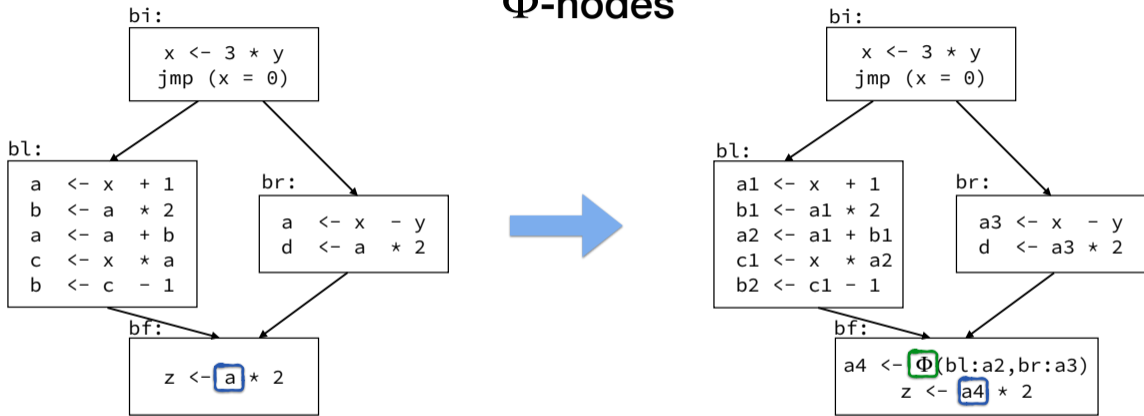


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Converting merging points: Φ -nodes



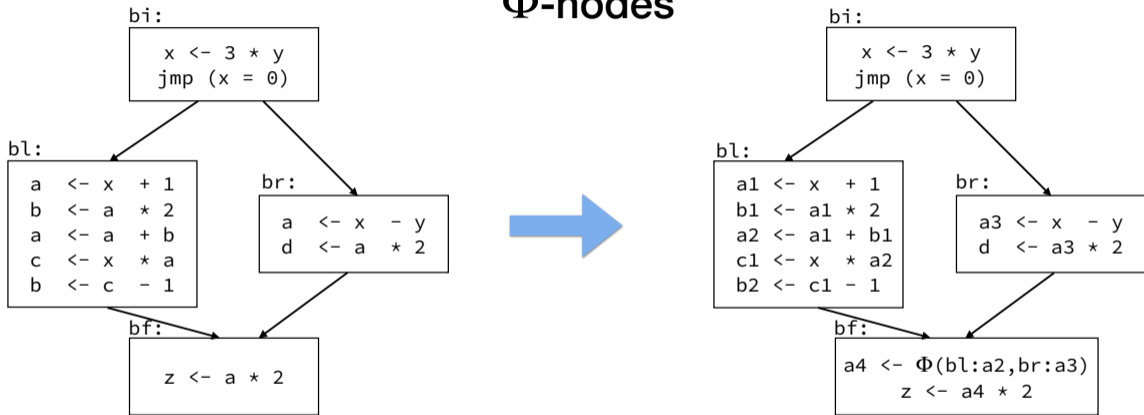
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Rule 3: at merge points, introduce Φ -nodes

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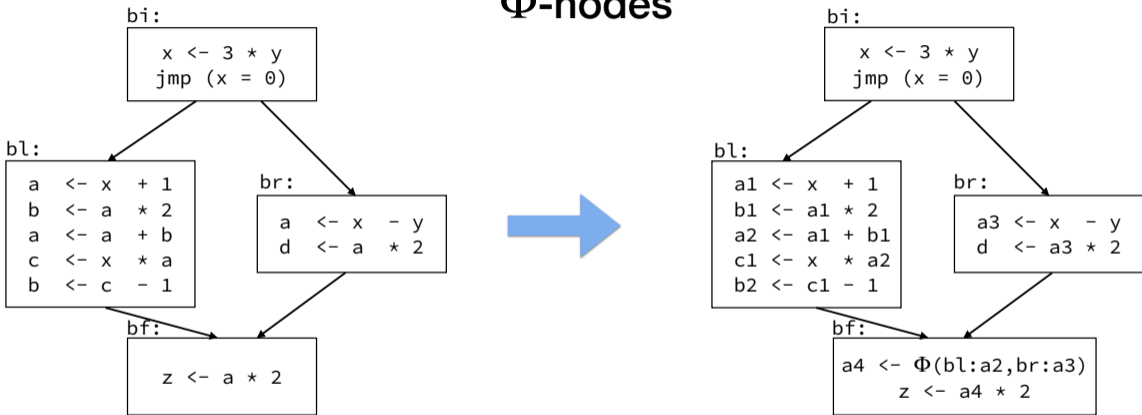
Φ -nodes



Goal: to decide when to introduce Φ -nodes

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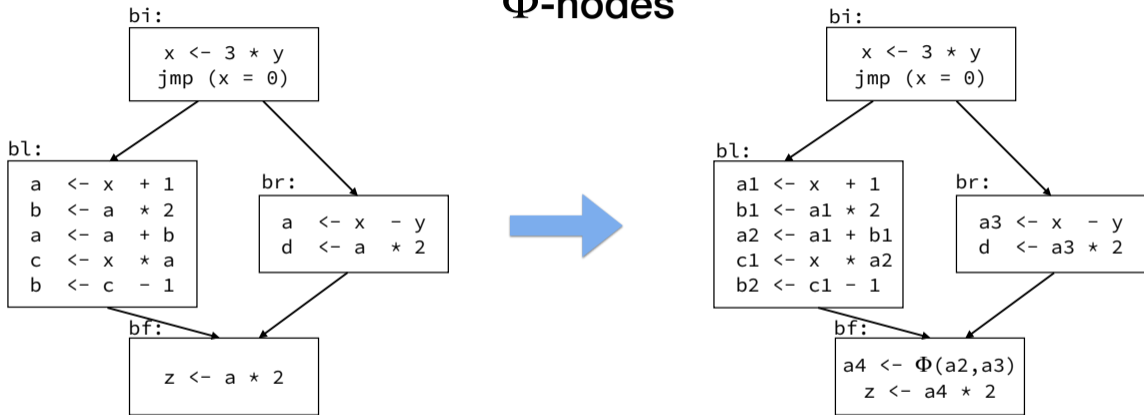
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One per variable at every join point?

Converting merging points: Φ -nodes



Goal: to decide when to introduce *few* Φ -nodes

One per variable at every join point?

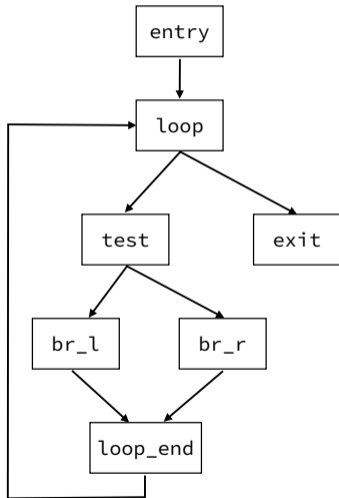
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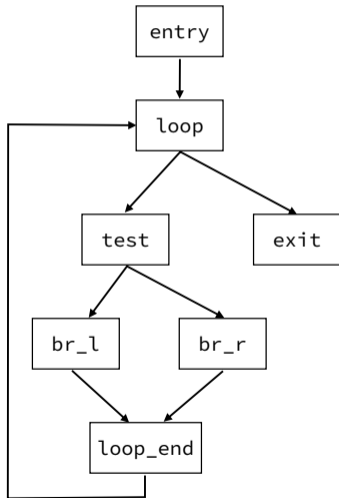
The domination relation

A dominates B if any path from entry to B contains A



The domination relation

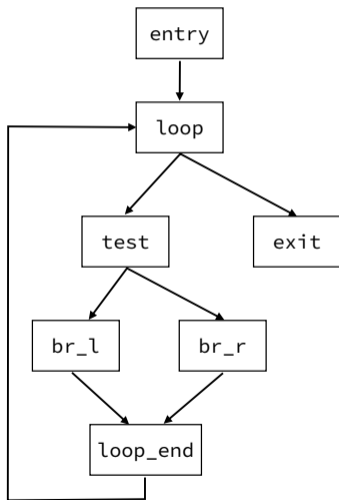
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Can you annotate the nodes with their dominators?

The domination relation

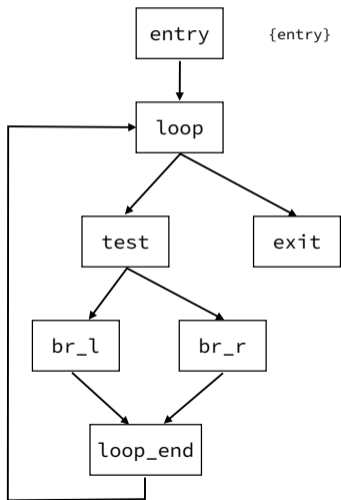
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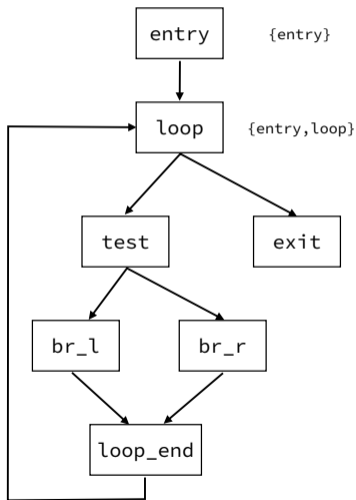
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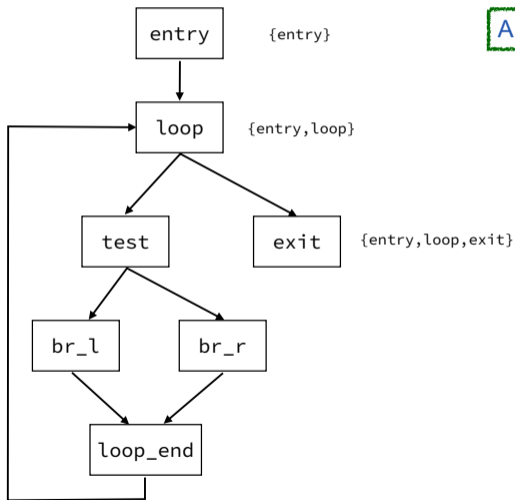
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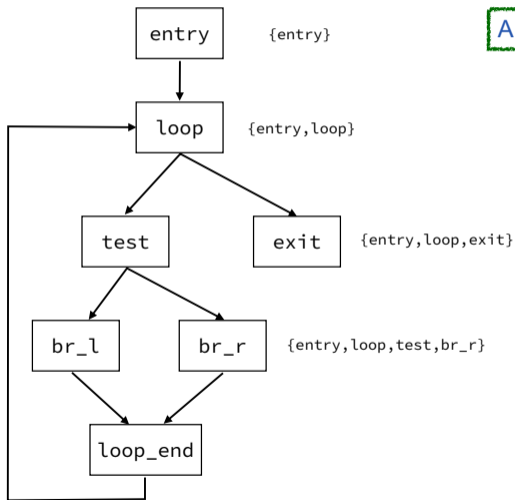
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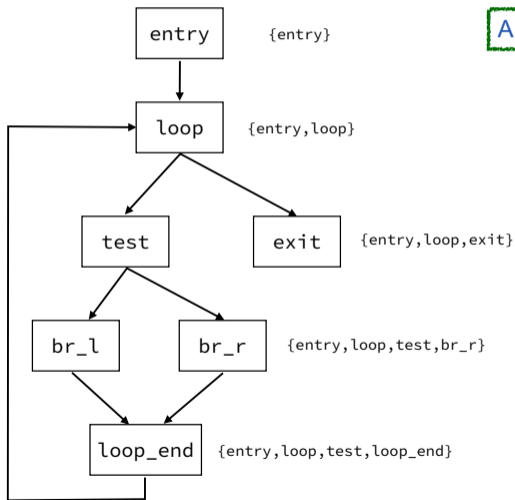
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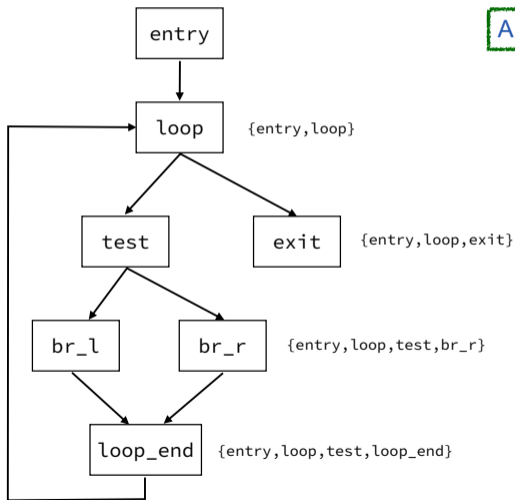
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A dominates B if any path from entry to B goes through A

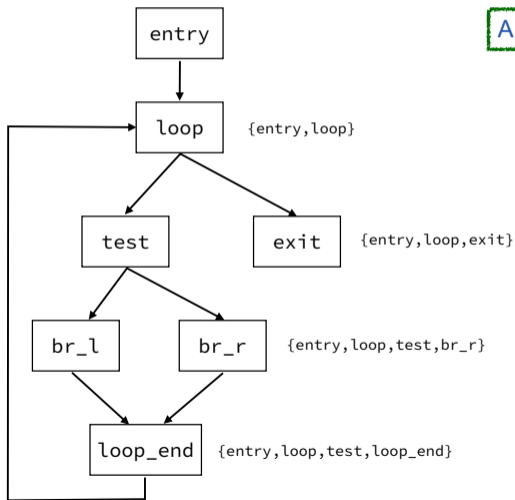
A *strictly dominates* B if A dominates B and A is not B

The *domination tree* stores the domination relation

A is parent to B if:

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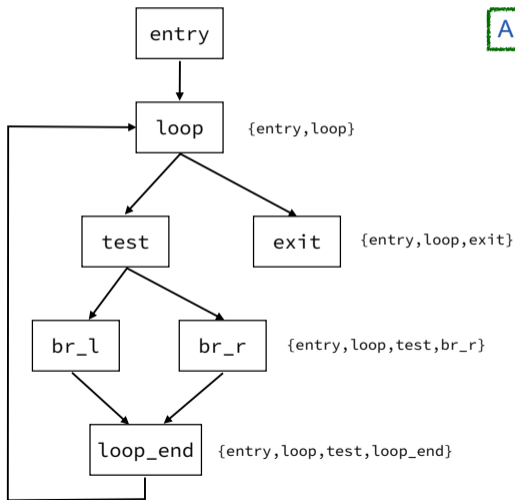
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Can you build the domination tree of the CFG to the left?

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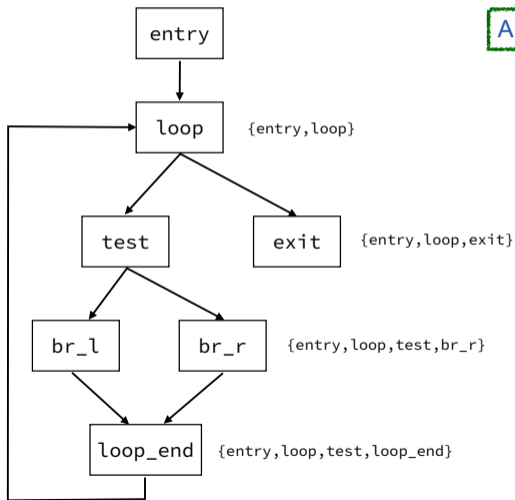
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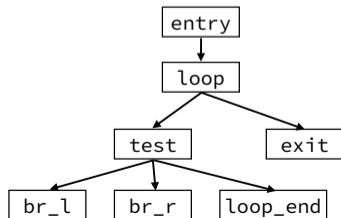
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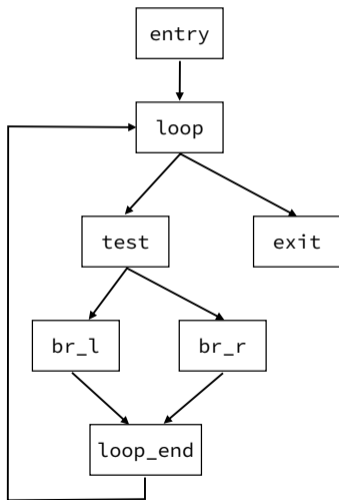
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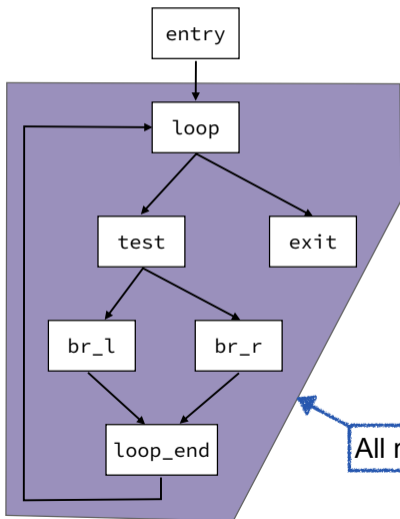
Dominance frontier



B belongs to **A**'s *dominance frontier* if:

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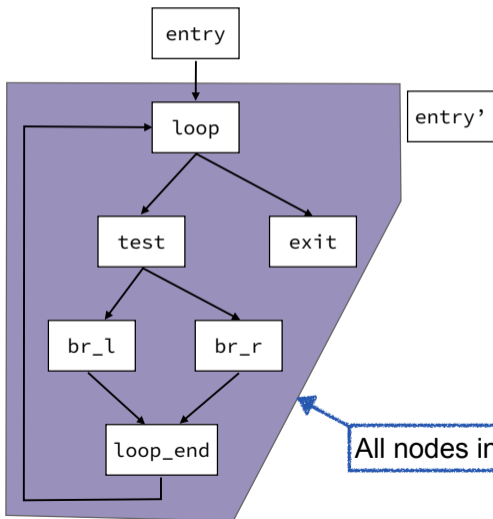
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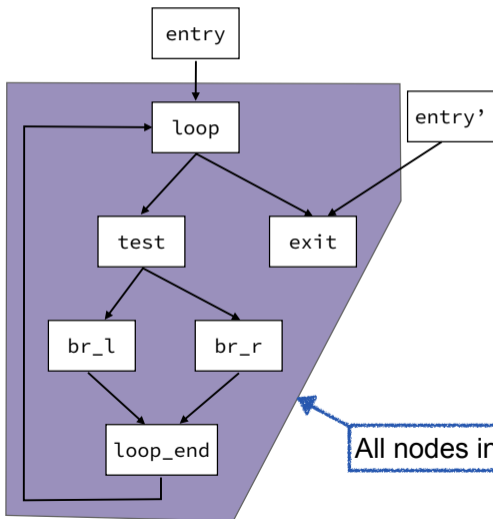
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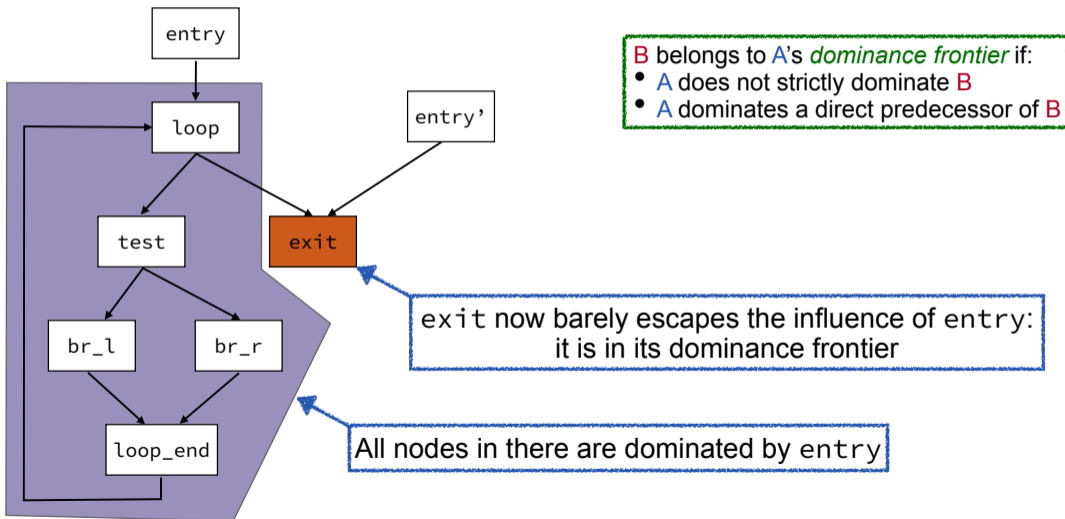
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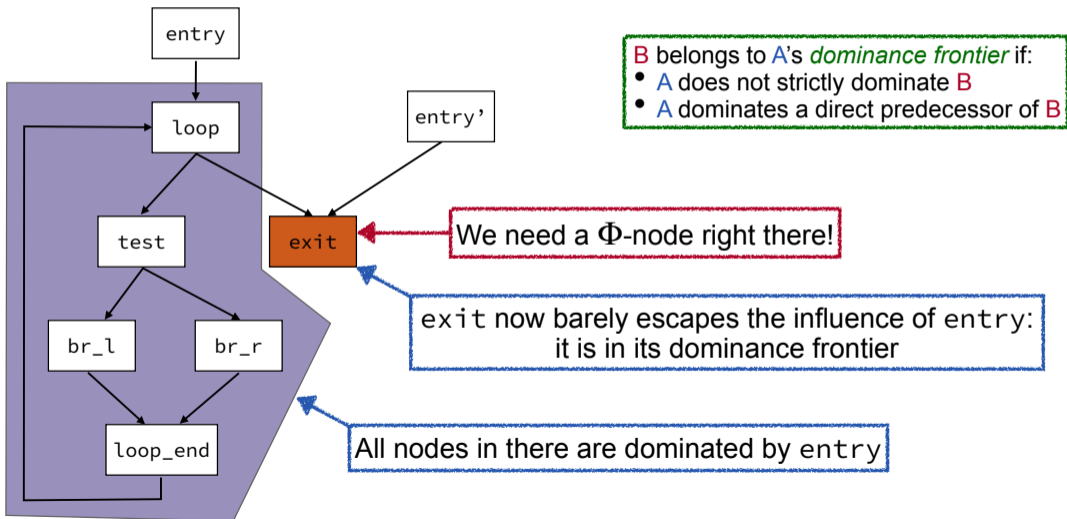
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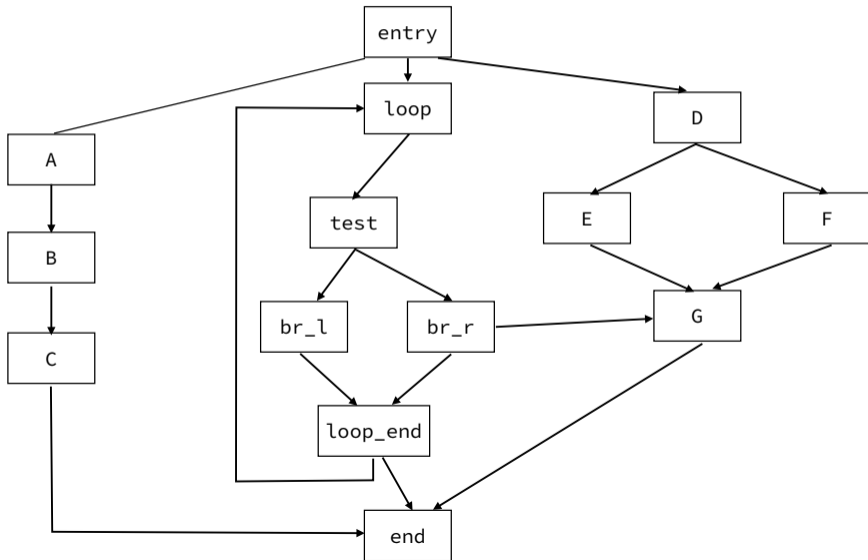
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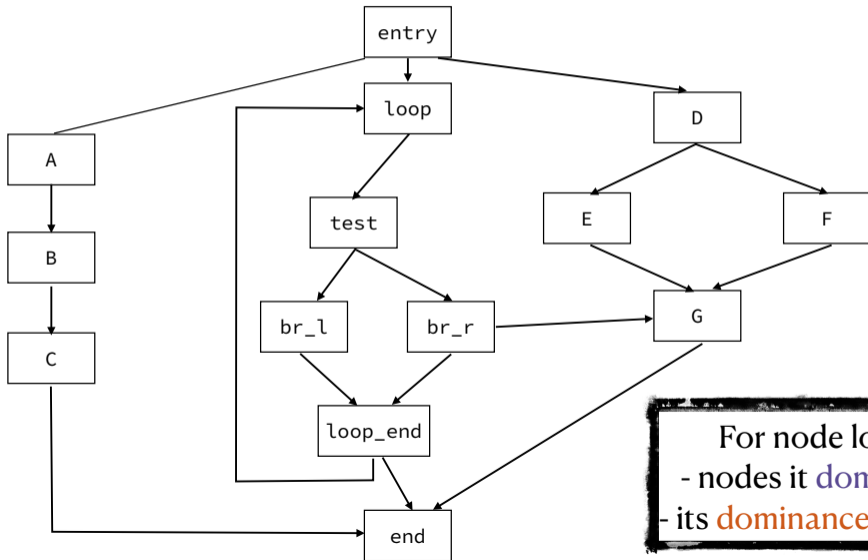
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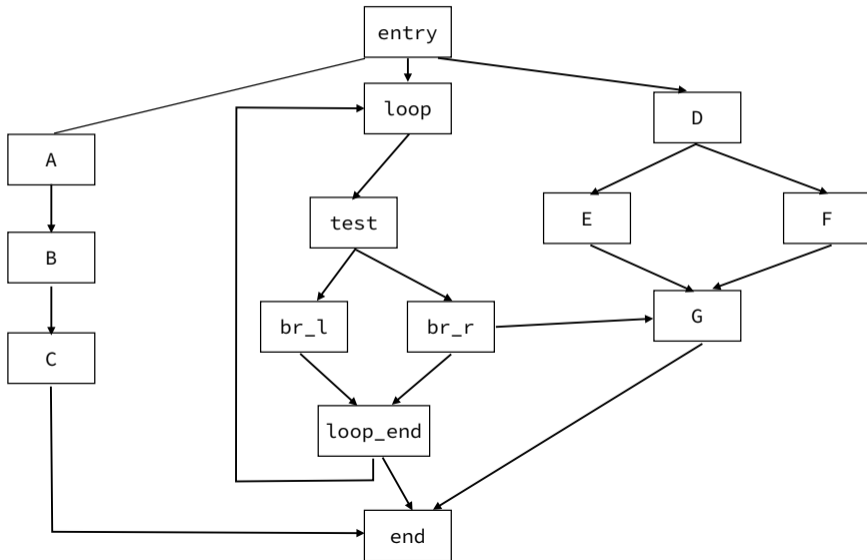
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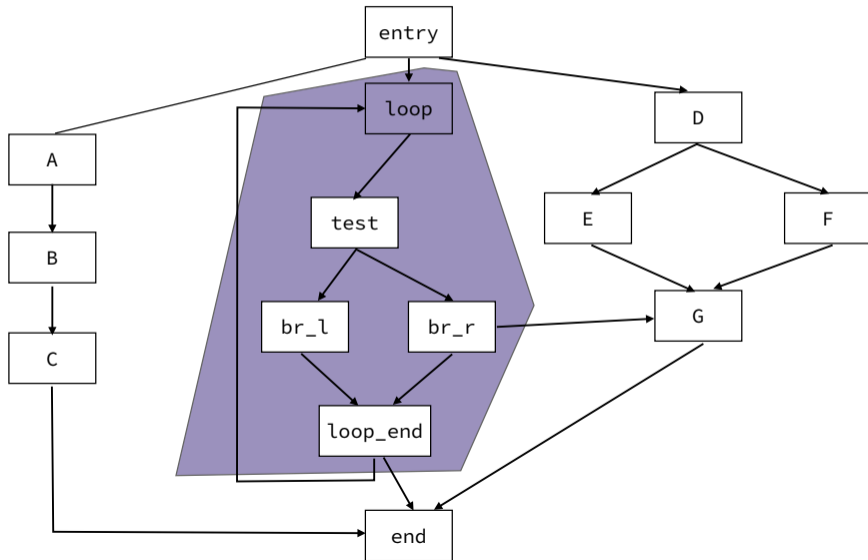
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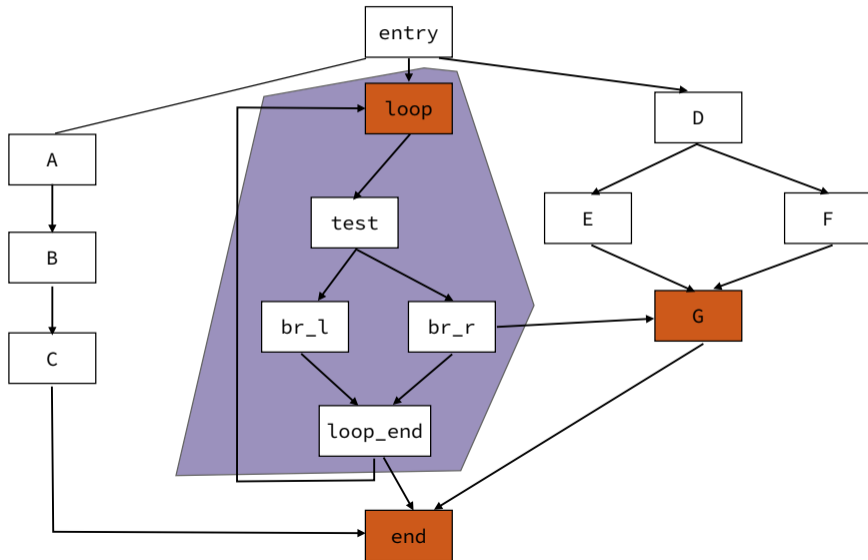
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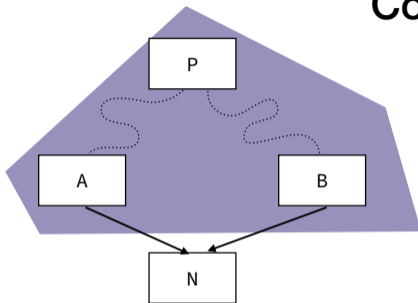
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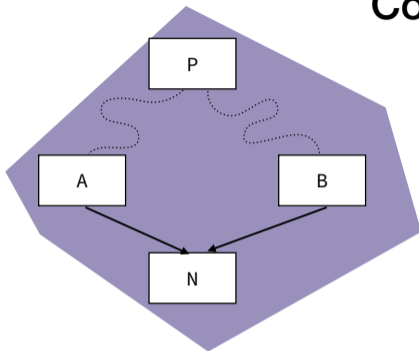


Computing dominators



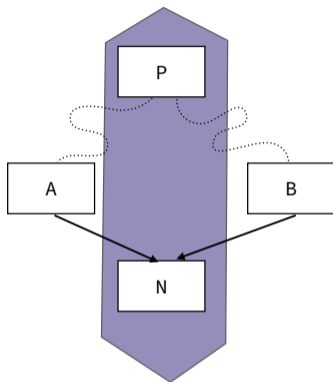
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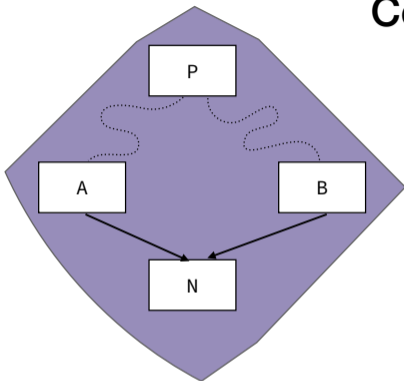
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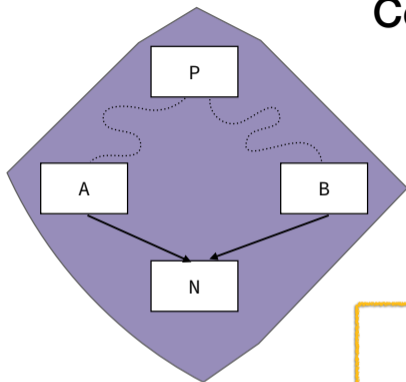
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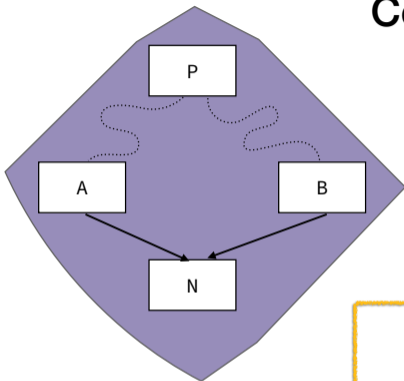
Let $D[n]$ be the set of nodes dominating n

$$D[\text{entry}] \triangleq \{\text{entry}\}$$

$$D[n] \triangleq \{n\} \cup \left(\bigcap_{p \in \text{pred}(n)} D[p] \right)$$

As is traditional, this system of equations can be solve by iteration¹

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Complexity?

¹: For a more efficient algorithm, see Lengauer and Tarjan's 1979

"A fast algorithm for finding dominators in a flowgraph"

Computing the dominance frontier

G : ambient cfg

DT: Dominance Tree of G

DF: map from nodes to sets of nodes

`computeDF(n) ::=`

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“Obvious”, immediate frontier



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for c in $\text{children}(n)$ in DT :

`computeDF(c)`

 for each w in $DF[c]$:


 if n does not dominate w :

$S \leftarrow S \cup \{w\}$

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The rest of the frontier is inherited from the other children



Computing the dominance frontier

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DF ::= computeDF(entry)

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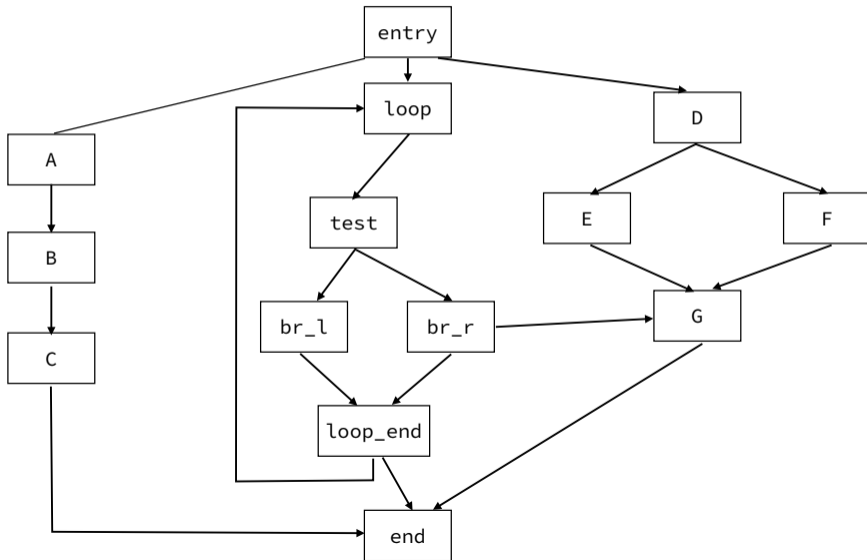
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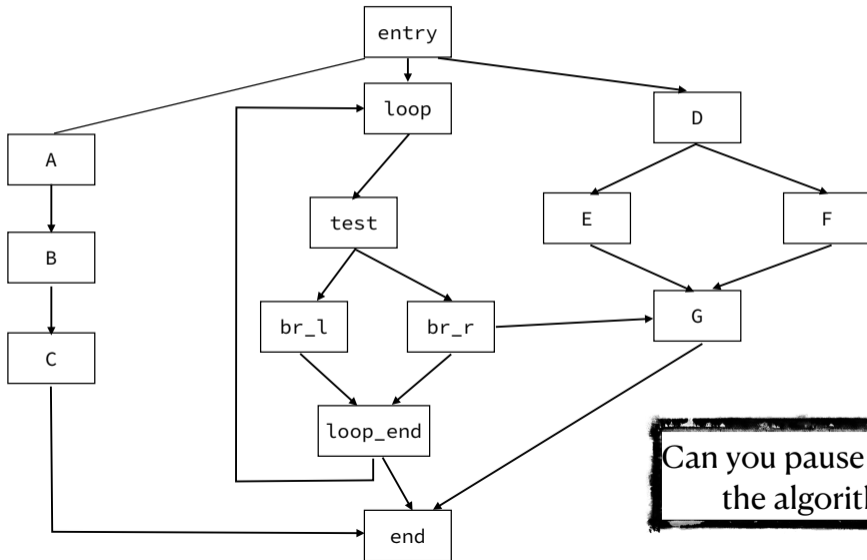
We kickstart the pass from the entry



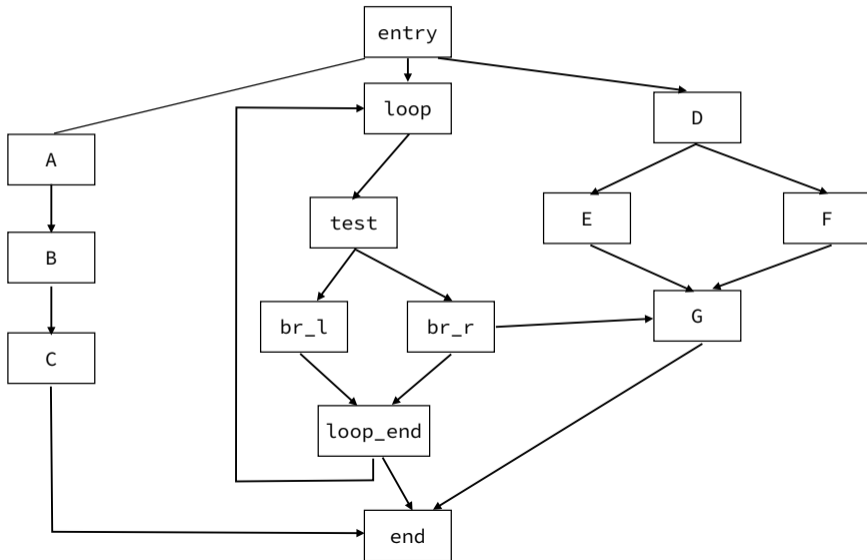
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Computing the dominance frontier



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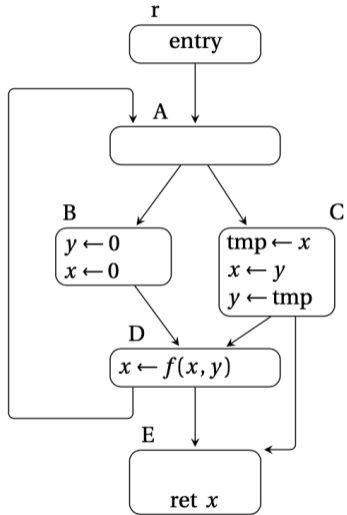


Taking stock

We want to convert a cfg to SSA-form

- The key difficulty is to figure out *where* exactly Φ -nodes are needed
- We observed *the dominance frontier* of a node seems to be the right notion
- We saw how to construct the dominance frontier, based on the construction of *the dominance tree*

We can now turn to the construction!



Inserting Φ -nodes

Insert-phi ::=

for x in Vars:

 for d in Defs(x):

 for b in DF(d):

 if there are no Φ -node associated to x in b :


 add one such Φ -node

 add b to Defs(x)

Inserting Φ -nodes

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We have not yet renamed: x can have several def-sites



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A Φ -node is a new definition site!

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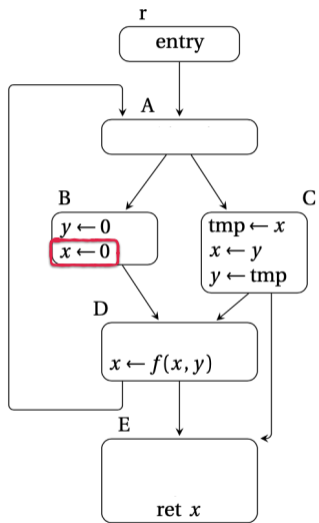
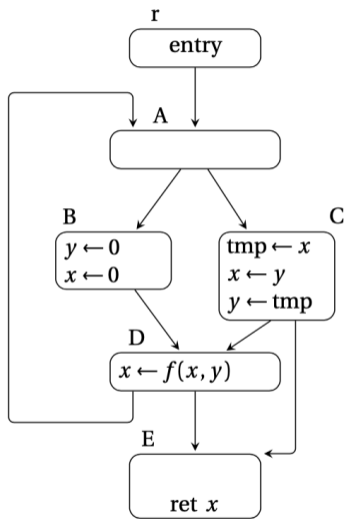
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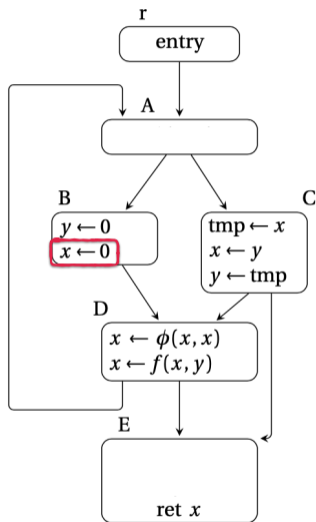
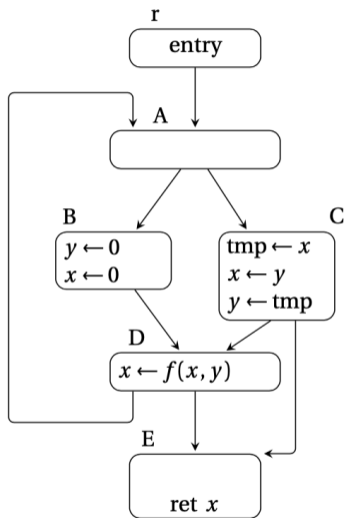
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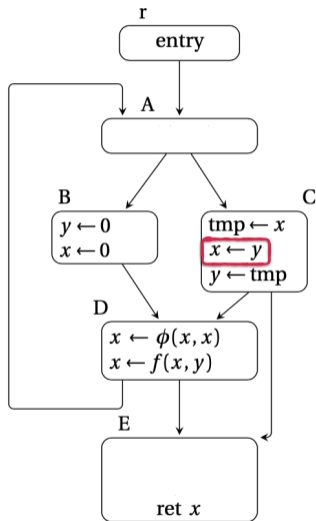
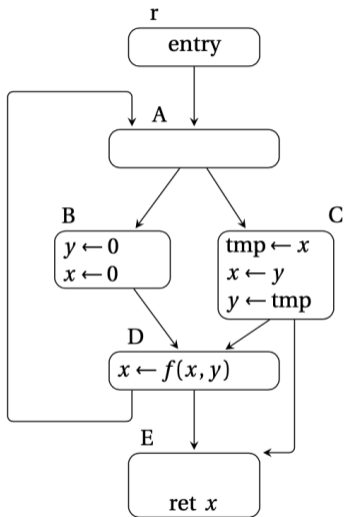
Blocks containing at least one def-site of x

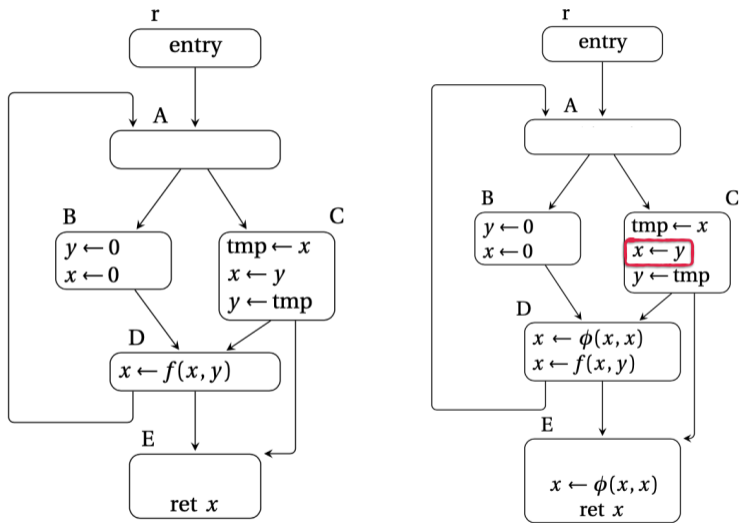
A Φ -node is a new definition site!

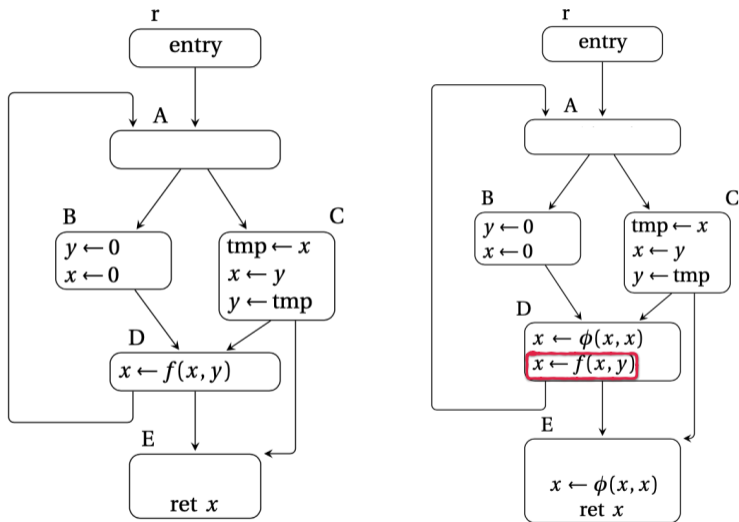
Convince yourself it converges!

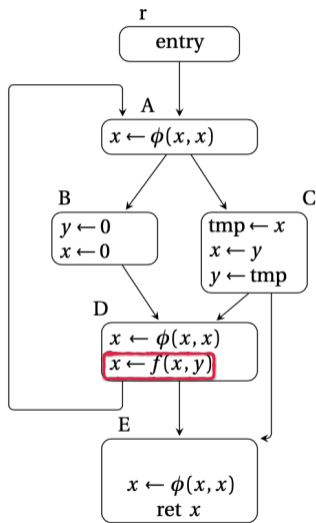
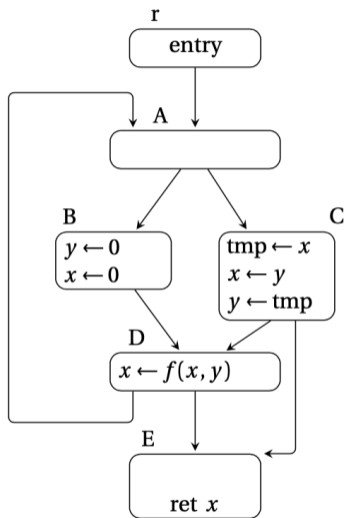


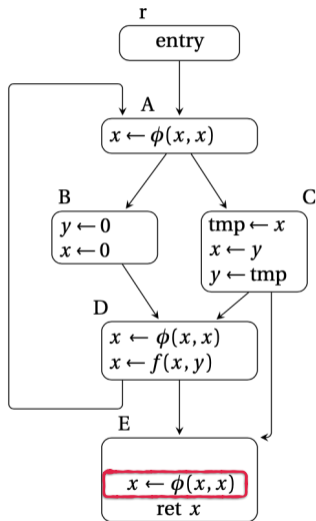
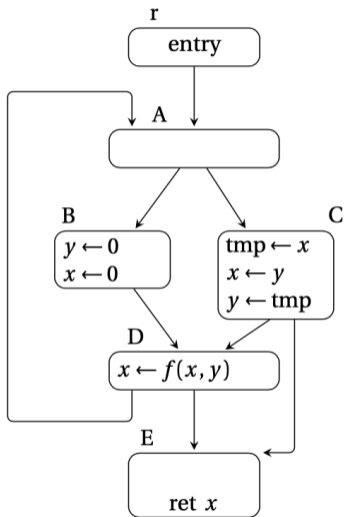


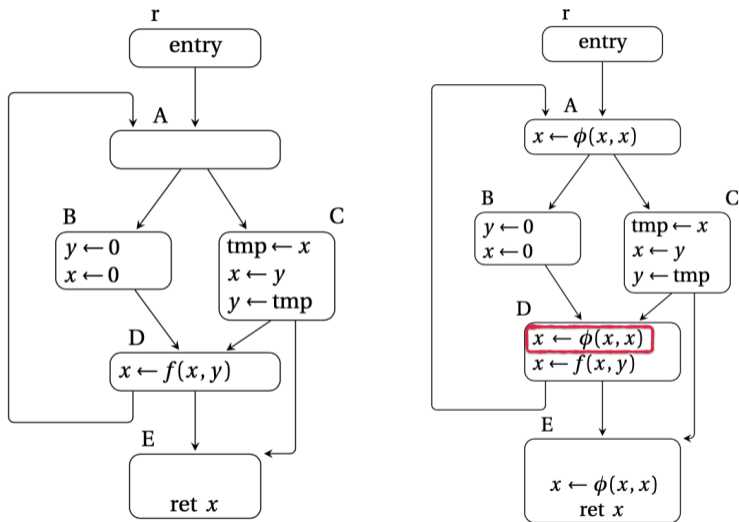


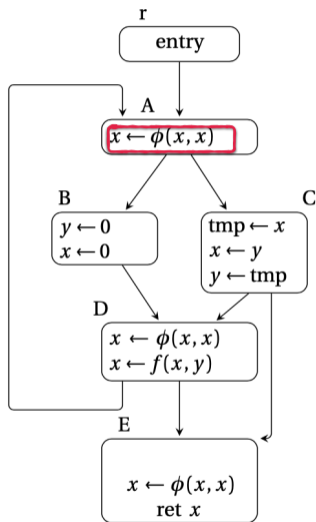
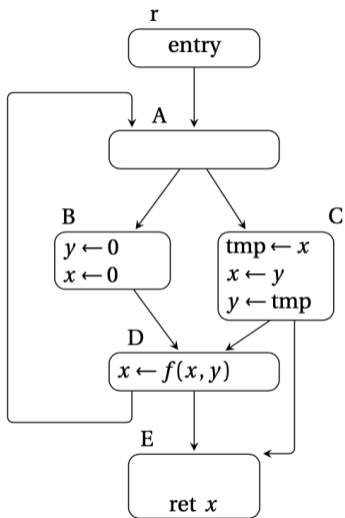


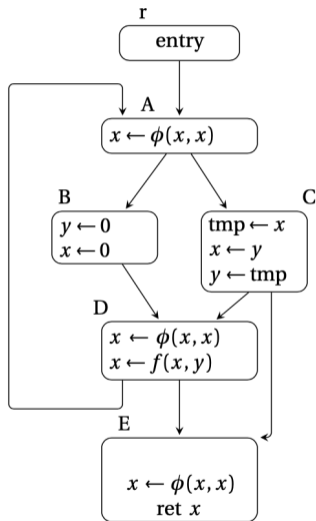
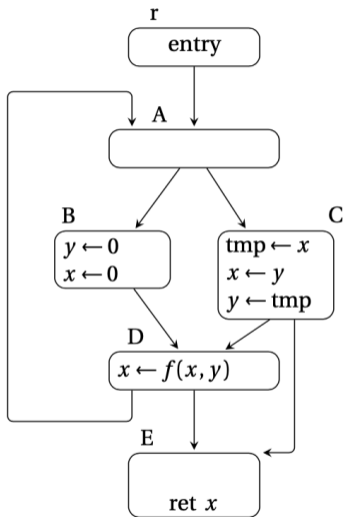


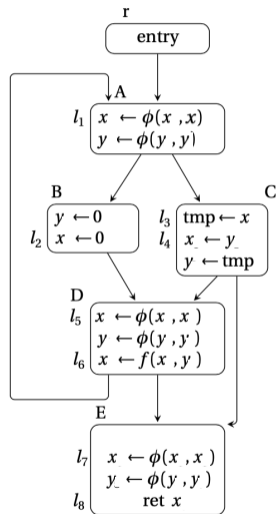
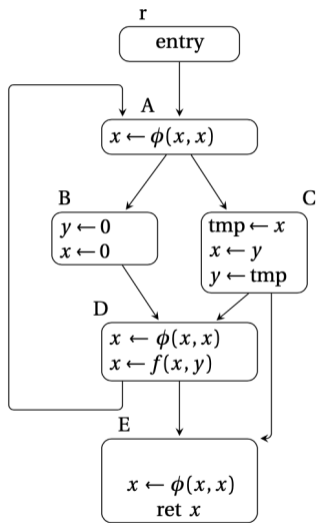
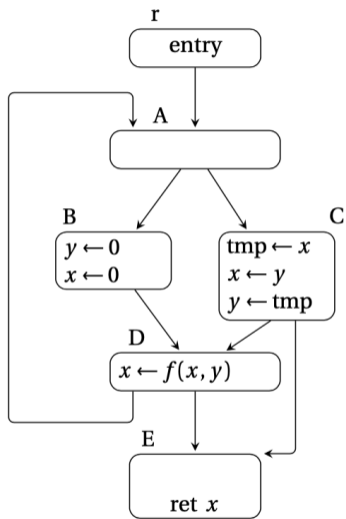












Renaming variables

`stack[x]` : for each variable, we maintain a stack of names (“x_i”)

`rename_aux(block) ::=`

`rename() ::= rename_aux(entry)`

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for `ins := y <- e` in `instr(block)`:

for each var `x` in `e`, replace `x` by `stack[x]`

generate a fresh name `y'` for `y`

push `y'` on top of `stack[y]`

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for each `s` successor of `block`:

for each Φ -node `p` of `s`:

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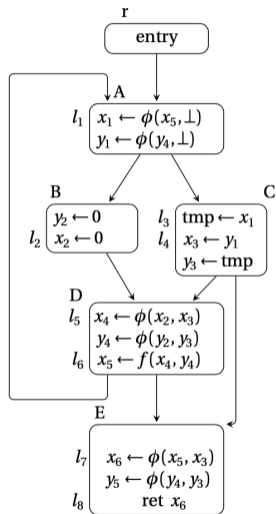
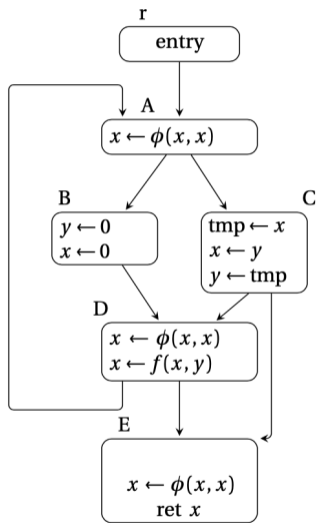
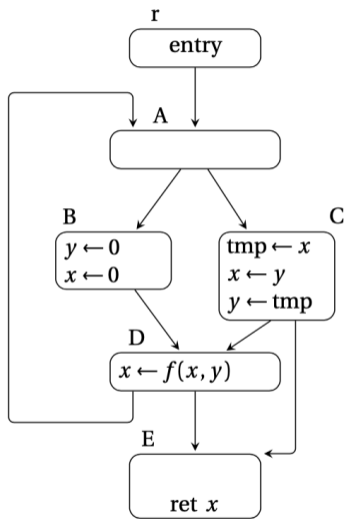
if `x` is read coming from `block`, replace `x` with `stack[x]`

for each successor `b` of `block` in the DT:

`rename_aux(b)`

pop from `stack` all variables introduced in this function call

`rename()` ::= `rename_aux(entry)`



Converting out of SSA form

From SSA to machine code

Processors do not support Φ -nodes, we need to compile them away!

From SSA to machine code

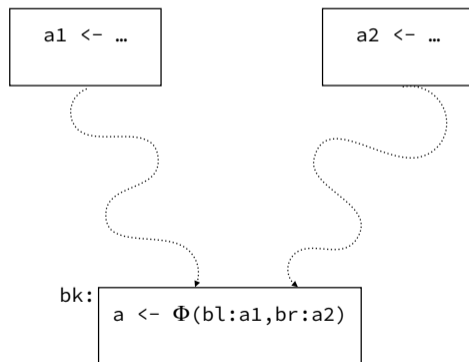
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bk:

<code>a <- Φ(bl:a1,br:a2)</code>

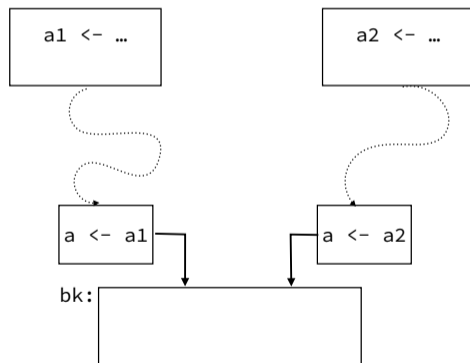
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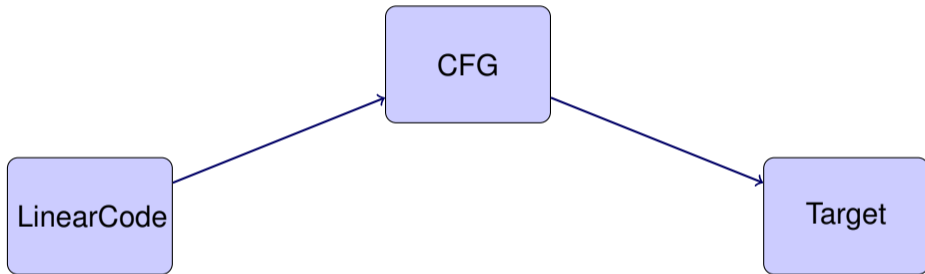


A good register allocator should then take care of eliminating needlessly introduced mov

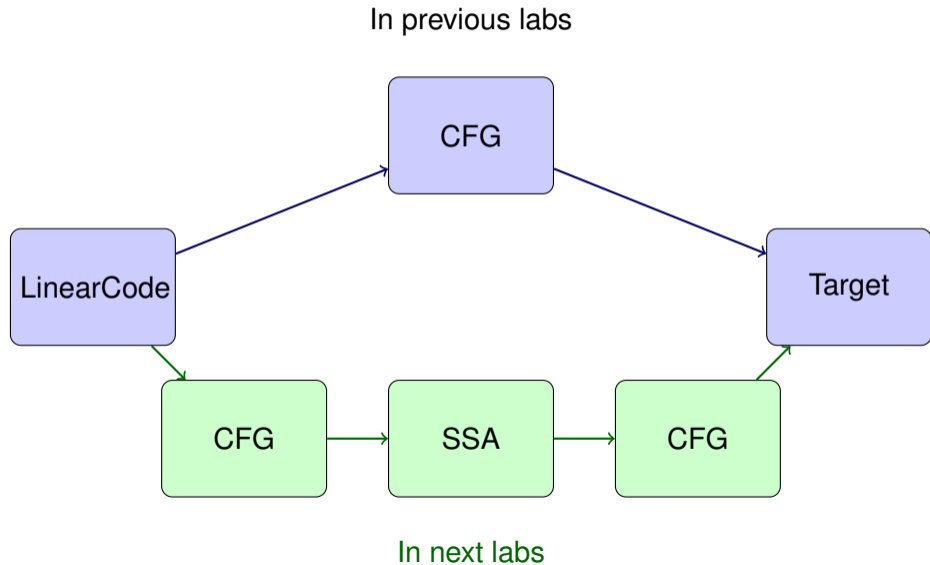
- 1 SSA Control Flow Graph
- 2 LAB: CFG + SSA
- 3 Exercises

Code Generation

In previous labs



Code Generation



Steps

- 1 Implement Leader algorithm (from Linear code to CFG)
- 2 Implement SSA entry (dominance frontier and ϕ -insertion)
- 3 Implement SSA exit

- 1 SSA Control Flow Graph
- 2 LAB: CFG + SSA
- 3 Exercises

To SSA and back again

```
i=1; j=1; k=0;
while (k < 100) {
  if (j < 20) {
    j=i;
    k=k+1;
  } {
    j=k;
    k=k+2;
  }
}
return j;
```

(Exercise taken from Fernando Pereira)

- 1 Draw the CFG
- 2 Compute the Dominance Tree and the Frontier
- 3 Convert to SSA
- 4 Convert out of SSA

To SSA and back again

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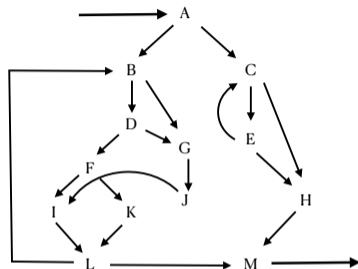
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```


Testing dominance in constant time

We wish to test in constant time whether a given node dominates another. We assume that we have already computed the dominance tree, and allow ourselves to this end a little pre-processing.

Q1. Draw the dominance tree of the graph on the right



Q2. Write an instrumented depth-first traversal labeling each node of the dominance tree with two numbers:

- N: the order in which that node was visited
- A: the maximum N among the node's descendants

Q3. Prove that these annotations can be used to test dominance in constant time.

Summary

- 1 SSA Control Flow Graph
- 2 LAB: CFG + SSA
- 3 Exercises